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#### INTRODUCTION

When planning a sample, allocating it to strata is a central problem. One tries to achieve a sample with least possible cost that provides estimates with sampling errors no larger than specified goals. When only one mean or proportion is estimated, with specified sampling error, the problem is a classical one [Cochran (1953), p. 75]. When several upper bounds on sampling errors are specified, the problem is more complex, but it has been solved by non-linear mathematical programming [Kokan (1963), Jagannathan (1965), Schwartz (1978)]. An interesting and powerful method of this kind is geometric programming [Duffin, Peterson and Zener (1967), Beightler and Phillips (1976), Ecker (1980)]. In this paper, it is applied to the allocation of stratified samples when several constraints on sampling errors and sample sizes are imposed. An example from the allocation of integrated samples [Schwartz, (1978)] is used to illustrate the method. Allocations with complex variance constraints and constraints requiring equal workloads over time are also shown. They were prepared for use by the Redetermination Review Svstem for quality control in the Supplemental Security Income program of the Social Security Administration of the United States of America.

#### STRATIFIED SAMPLE ALLOCATION

Optimum allocation in stratified random sampling is discussed by Cochran (1953). In his notation (p. 66), a population of N items is di-d vided into L strata, indexed by h. The population sizes  $N_{\mbox{\scriptsize h}}$  are known. Also known, or estimated externally, are variances  $S_{\bf k}^{\bf Z}$  and costs per sampled unit  $C_{\bf k}$  in each stratum. A sampling allocation consists of choices of  $n_{\bm{h}},$  the sample size in each stratum. Clearly,  $0 \leq n_h \leq N_h,$ since the sample cannot be larger than the population.

The cost of the entire sample is  $C = a + \sum_{n=1}^{\infty}$  $C_h n_h$ , where a is an overhead cost. The variance of the estimate of the mean is  $V(\vec{q}_{st}) = \frac{1}{N^2} \sum_{k=1}^{N_h} N_h (N_k - n_h) \frac{S_h^2}{n_h}$ 

An optimal sample allocation is found by minimizing the variance V with respect to the sample sizes n, subject to fixed cost Co. Using a Lagrange multiplier, one minimizes  $\mathbf{V}$  +  $\boldsymbol{\lambda}$  (C-C<sub>O</sub>). An alternative is to minimize the cost C with respect to the  $\mathbf{M}_{\mathbf{h}}$  , subject to a fixed variance  $\mathbf{V}_{\mathbf{O}}.$ Then one minimizes  $C + \chi'(V-V_C)$ , an equivalent problem. Actually, the constraint on the variance then specified could be found at the same minimal cost. If several variance constraints are imposed, the cost of sampling is minimized. Several constraints imply several terms with Lagrange multipliers in the quantity to be minimized. Some constraints, however, do not actively constrain the problem, even though they are satisfied. Then their Lagrange multipliers are zero. Lagrange multipliers for active constraints are like weights expressing the importance of the

constraints. They are also the variables in the dual problem of geometric programming, by means of which we allocate samples.

#### GEOMETRIC PROGRAMMING

Developed in an engineering context by Duffin, Peterson and Zener (1967), geometric programming is a technique for minimizing a function called a "posynomial" subject to several constraints consisting of "posynomials" being less than or equal to 1. A "posynomial" is a polynomial in several variables with positive coefficients in all terms. The powers to which the variables are raised can be any real numbers. Both the cost function and the variance constraint functions are "posynomials", so geometric programming is applicable to these allocation problems.

Geometric programming transforms the primal problem of minimizing a "posynomial" subject to "posynomial" constraints to a dual problem of maximizing a function of the weights on each constraint. Usually, there are fewer constraints than strata, so the transformation simplifies. Exhibit 1, copied from Duffin, Peterson and Zener (1967, pp. 78-81) defines geometric programming concisely. Ecker (1980) reviews the extensive literature.

Application of geometric programming to allocation is best described in an example. First, allocation of sampling units to strata in an integrated sample is stated as a problem. Second, the problem is interpreted as a primal problem in geometric programming. Third, the dual problem is found by transforming from the primal problem. Fourth, the dual problem is solved, partly analytically and partly by an iterative numerical calculation.

# ALLOCATION IN INTEGRATED SAMPLING

Schwartz (1978) designed an integrated sample combining quality control samples from three welfare programs of the U.S. Federal Government: Aid to Families with Dependent Children (AFDC), Food Stamps (FS) and Medicaid (Md). Seven strata were identified, including families with all possible combinations of assistance. Three variance constraints were established, to achieve acceptable estimates of the proportions of errors in each program. Population sizes, costs and variance constraint coefficients were:

Stratum	Population Size, H <sub>h</sub>	Cost hours	Variance 1 AFDC	constrair 2 FS	t poeff. 3 Md	Cost times 1 AFDC	variano 2 PS	e coeff. 3 Må
1 APDC	9,000	9.5	67.01	0	0	636.27	0	0
2 AFDC,PS	18,000	11.5	294.55	119.83	0	3387,27	1378.01	0
3 MPDC,FS,M6	2,000	13.5	2,97	2.15	0.27	40,15	29.00	3.59
4 AFDC,MG	1,000	11.5	0.66	0	0.10	7.56	٥	1.10
5 <b>PS</b>	23,000	9.5	0	312.20	0	0	2965.87	0
6 PS,Md	7,000	11.5	0	23.65	3.38	0	271.96	38.87
7 MA	45,000	9.5	0	0	193.10	0	0	1834.47

#### PRIMAL PROBLEM

Minimize  $g_0(t) = 9.5t_1 + 11.5t_2 + 13.5t_3 + 11.5t_4 + 9.5t_5 + 11.5t_6 + 9.5t_7$ 

subject to

$$g_1(t) = 67.01t_1^{-1} + 294.55t_2^{-1} + 2.97t_3^{-1} + 0.66t_4^{-1}$$
  
 $\leq 1$ 

$$g_2(t) = 119.83t_2^{-1} + 2.15t_3^{-1} + 312.20t_5^{-1} + 23.65t_6^{-1}$$
  
 $\leq 1$ 

$$g_3(t) = 0.27t_3^{-1} + 0.10t_4^{-1} + 3.38t_6^{-1} + 193.10t_7^{-1}$$
 $\leq 1$ 

where  $t_h = n_h = sample size in stratum h.$ 

#### DUAL PROBLEM

Maximize 
$$\ln v(s) = \frac{636.27 s_1}{636.27 s_1} + \frac{1378.01 s_2}{1387.27 s_1} + \frac{1378.01 s_2}{1387.27 s_2} + \frac{1378.01 s_3}{1387.27 s_3} + \frac{1387.27 s_2}{13887 s_3} + \frac{1384.47 s_3}{1384.47 s_3} + \Lambda (s_1 + s_2 + s_3 - 1)$$

The  $\S$ 's are weights, one for each constraint, which must add to one. Their coefficients are costs multiplied by variance constraint coefficients. This expression is derived analytically in this special case from the general dual expression in Exhibit 1. Computational methods for solving dual problems are described in Rosen (1960) Dinkel, Kochenberger and McCarl (1974) and Dinkel, Elliott and Kochenberger (1977). A slow, but simple and serviceable, method iterates to a solution:  $\S_1 = .34232$   $\S_2 = .54582$   $\S_3 = .11186$ 

In substituting these values of the \$'s into  $\ln \ v(\$)$ , each term is the quantity used to calculate the optimum sample size and its cost:

Stratum number	term	c <sub>h</sub> (	$t_h = n_h = (14rm)/(2(14rms)/Ch$
1	14.76	9.5	206
2	43.73	11.5	504
3	5.47	13.5	54
4	1.65	11.5	19
5	40.23	9.5	561
6	12.36	11.5	142
7	14.32	9.5	200
sum	132,52		1686

Optimum sample sizes are calculated by multiplying each  $\sqrt{\phantom{a}}$  term by their sum and dividing each by  $C_h$ ,—its cost. The total sample size is 1686. The total cost is 17,563 hours, equal to ( $\sqrt{2}$ ) terms) except for rounding up the sample sizes to integers. Checking the primal problem, using  $t_h$ ,  $g_0(t) = 17,563$  hours,  $g_1(t) = 0.99945$ ,  $g_2(t) = 1.00062$ ,  $g_3(t) = 0.99957$ , so the variance constraints are satisfied.

Programs written in Basic are available for this special case, which was used as a test case and an expository example.

# ALLOCATION OF REDETERMINATION REVIEW SYSTEM SAMPLES

Exhibit 2 shows allocations of samples developed by geometric programming. The sample size per month and region is minimized subject to several constraints on variances of proportions of defective cases taken over several months. In addition to variance constraints, sample sizes per region per month are required to be equal over months, to stabilize workloads. To achieve this, a common upper bound t\* on the monthly sample sizes for each region is minimized. The monthly sample sizes for areas within a region are the variables  $t_h$  in the primal problem. They are not necessarily equal over months, but they are constrained by "posynomial" constraints to add to a sum less than or equal to t\*. The constraints are:  $t_1t^{*-1} + t_2t^{*-1} + \ldots + t_9t^{*-1} \stackrel{<}{\sim} 1$ 

The resulting primal geometric program is more intricate and larger than the expository problem drawn from Schwartz (1978), but the same methods are used to solve it.

In Exhibit 2, allocated sample sizes are shown. Total sample sizes per region are nearly equal, for each month, as specified. At the end of Exhibit 2, expected sampling errors are shown for each area over nine months and also over the six sets of four consecutive month "rolls". The samples were designed to produce 4% expected sampling errors over nine months. Those calculated from the allocations range from 3.96% to 3.99%.

#### COMPUTER PROGRAMS

Several programs have been written in APL to produce these allocations and similar ones. Write for details to Dr. Miles Davis, 1214 Bolton Street, Baltimore, Maryland 21217, U.S.A.

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## EXHIBIT 1

from Duffin, Peterson & Zener (1967) pp. 78-81.

#### 1. PRIMAL PROGRAMS AND DUAL PROGRAMS

We begin this section by presenting the most general primal program.

Primal Program A. Find the minimum value of a function g<sub>0</sub>(t) subject to the constraints

$$t_1 > 0, \quad t_2 > 0, \quad \dots, \quad t_m > 0$$
 (1)

and

$$g_1(t) \le 1, \quad g_2(t) \le 1, \quad \dots, \quad g_p(t) \le 1.$$
 (2)

Here

$$g_k(t) = \sum_{i \in H_{k1}} c_i t_1^{a_{11}} t_2^{a_{12}} \cdots t_n^{a_{in}}, \quad k = 0, 1, ..., p,$$
 (3)

where

$$J[k] = \{m_k, m_k + 1, m_k + 2, \dots, n_k\}, \qquad k = 0, 1, \dots, p, \quad (4)$$

and

$$m_0 = 1$$
,  $m_1 = n_0 + 1$ ,  $m_2 = n_1 + 1$ , ...,  $m_p = n_{p-1} + 1$ ,  $n_p = n$ .

The exponents  $a_{ij}$  are arbitrary real numbers, but the coefficients  $c_{ij}$  are assumed to be positive. Thus the functions  $g_{ij}(t)$  are posynomials.

The posynomial to be minimized, namely  $g_0(t)$ , is termed the *primal function*, and the variables  $t_1, t_2, \ldots, t_n$  are called *primal variables*. The constraints imposed by (1) are termed manual constraints, whereas those imposed by (2) are called *forced constraints*. Collectively, these constraints are referred to as *primal constraints*.

The matrix  $(a_{ij})$  is termed the exponent matrix. It has n rows and m columns.

The dual program corresponding to primal program A is the following:

Dual Program B. Find the maximum value of a product function

$$v(\delta) = \left[\prod_{i=1}^{n} \left(\frac{c_i}{\delta_i}\right)^{\delta_i}\right] \prod_{k=1}^{p} \lambda_k(\delta)^{\lambda_k(\delta)}, \quad (6)$$

where

$$\lambda_{\mathbf{n}}(\mathbf{\delta}) = \sum_{i \in I(k)} \delta_{i}, \qquad k = 1, 2, \dots, p. \tag{7}$$

Here

$$J[k] = \{m_k, m_k + 1, m_k + 2, \ldots, n_k\}, \quad k = 0, 1, \ldots, p, (8)$$

where

$$m_0 = 1$$
,  $m_1 = n_0 + 1$ ,  $m_2 = n_1 + 1$ , ...,  $m_p = n_{p-1} + 1$ ,  $n_p = n$ . (9)

The factors  $c_i$  are assumed to be positive and the vector variable  $\delta = (\delta_1, \ldots, \delta_n)$  is subject to the linear constraints:

$$\delta_1 \geqslant 0, \quad \delta_2 \geqslant 0, \quad \dots, \quad \delta_n \geqslant 0,$$
 (10)

$$\sum_{i=1}^{\infty} \delta_i = 1, \tag{11}$$

and

$$\sum_{i=1}^{n} a_{ij} \delta_{i} = 0, \qquad j = 1, 2, \dots, m.$$
 (12)

Here the coefficients an are real numbers.

In evaluating the product function  $o(\delta)$ , it is to be understood that  $x^x = x^{-x} = 1$  for x = 0. This will make  $o(\delta)$  continuous over its domain of definition.

The product function  $v(\delta)$  is termed the dual function, and the variables  $\delta_1, \delta_2, \dots, \delta_n$  are called dual sariables. Relation (10) is termed the positivity condition, (11) is called the normality condition, and (12) constitutes the orthogonality condition. Collectively, these conditions are referred to as dual constraints.

Notice how dual program B is obtained from its corresponding primal program A. The factors  $c_1$  appearing in the dual function o(8) are the coefficients of the posynomials  $g_2(t)$ ,  $k=0,1,2,\ldots,p$ . We say that  $\delta_1$  is associated with the th term  $c_1t_1,\ldots,t_n$  of primal program A, so that each term of  $g_n(t)$ ,  $k=0,1,2,\ldots,p$ , is associated with one and only one of the dual variables  $\delta_1$ ,  $\delta_2$ , ...,  $\delta_n$ . Each factor  $\lambda_k(\delta)^{\lambda_k(\delta)}$  of  $v(\delta)$  comes from a forced constraint  $g_k(t) \leqslant 1$ . Notice that no such factor appears from the primal function because the normality condition forces  $\lambda_0(\delta)$  to be one. The normality condition is the only part of dual program B that distinguishes between the primal function  $g_0(t)$  and those posynomials  $g_2(t)$ ,  $k=1,2,\ldots,p$ , that appear in the forced constraints. Finally, it should be noted that the coefficient matrix  $(a_{ij})$  appearing in the orthogonality condition is simply the exponent matrix of primal program A.

#### 2. THE DUALITY THEORY

We say that a program (either primal or dual) is consistent if there is at least one point (vector) that satisfies its constraints. Primal program A is said to be superconsistent if there is at least one vector  $t^a$  that has positive components and the property

$$g_k(t^a) < 1, \quad k = 1, 2, ..., p.$$
 (1)

It should be noted that primal program A can be consistent without being superconsistent but that each superconsistent program is consistent.

In terms of the preceding concepts we state Theorem 1, which is called the first duality theorem of geometric programming and is the main theorem of the present formulation of geometric programming.

**Theorem 1.** Suppose that primal program A is superconsistent and that the primal function  $g_0(t)$  attains its constrained minimum value at a point that satisfies the primal constraints. Then

- (i) The corresponding dual program B is consistent and the dual function v(8) attains its constrained maximum value at a point which satisfies the dual constraints.
- (ii) The constrained maximum value of the dual function is equal to the constrained minimum value of the primal function.
- (iii) If t is a minimizing point for primal program A, there are non-negative Lagrange multipliers μ<sub>k</sub>, k = 1, 2, ..., p, such that the Lagrange function

$$L(t, \mu) = g_0(t) + \sum_{k=1}^{p} \mu_k[g_k(t) - 1]$$
 (2)

has the property

$$L(t',\mu) \leq g_0(t') = L(t',\mu') \leq L(t,\mu') \tag{3}$$

for arbitrary  $t_i > 0$  and arbitrary  $\mu_k \geqslant 0$ . Moreover, there is a maximizing vector  $\delta'$  for dual program B whose components are

$$\delta_{i}' = \begin{cases} \frac{c_{i}t_{i+1}^{n_{i+1}} \cdots t_{i+m}^{n_{i+m}}}{g_{0}(t)}, & i \in J[0], \\ \frac{\mu_{k}c_{i}t_{i+1}^{n_{i+1}} \cdots t_{i+m}^{n_{i+m}}}{g_{0}(t)}, & i \in J[k], & k = 1, \dots, p, \end{cases}$$
(4)

where t = t' and  $\mu = \mu'$ . Furthermore,

$$\lambda_{k}(\delta') = \frac{\mu_{k}'}{g_{O}(t')}, \quad k = 1, 2, ..., p.$$
 (5)

(iv) If 8' is a maximizing point for dual program B, each minimizing point t' for primal program A satisfies the system of equations

$$c_{i}I_{1}^{a_{1}}\cdots I_{m}^{a_{m}} \approx \begin{cases} \delta_{i}^{i} v(\delta^{i}), & i \in J[0], \\ \frac{\delta_{i}^{i}}{\lambda_{k}(\delta^{i})}, & i \in J[k], \end{cases}$$

$$(6)$$

where k ranges over all positive integers for which  $\lambda_k(\delta') > 0$ .

Relation (4) provides a formula for computing a maximizing vector  $\delta'$  from the knowledge of a minimizing vector t' and appropriate Lagrange multipliers  $\mu_{k'}$ ,  $k = 1, 2, \ldots, p$ . On the other hand, (6) gives a method for finding a minimizing vector t' from the knowledge of a maximizing vector  $\delta'$ . It should be mentioned that (6) is easily reduced to a system of linear equations in the variables  $\log t_i, j = 1, 2, \ldots, m$ , by taking the logarithm of both sides of each equation. Thus a minimizing point t' is easily found from a maximizing point  $\delta'$ . Finally, it should be noted from (5) that the numbers  $\lambda_k(\delta')$ , saide from a constant factor, are the Lagrange multipliers for primal program A.

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AREA I	MAR 76	APR 79	MAY 78	JUN 30	SAMPLE JUL 44	AUG 58	SEP ⊕8	0CT 60	NGV 50	SUM 598	AVE 66	1 2 3	200 184 157	313 288 246	258 237 2 <b>02</b>	271 249 212	219 201 171	241 221 189	154 142 121	156 143 122	126 116 99	1938 1731 1519	
2 4 5	69 57 61 60	94 65 49	45 40 69 <b>59</b>	63 62 58 58	68 50 57 61	64 93 63 60	60 61 74 69	75 53 64 73	62 84 63	590 561 563 583	66 62 63 65	SUM	541	847	697	732	591	651	417	421	341	5298	
5 7 8	60 45 64	81 75 68 62	65 58 67	57 72 87	73 70 49	52 75 65	57 69 52	72 61 76	62 79 63 51	595 581 573	66 65 64	REGIO	N 9 RANCISCO							ne	F RATE	CHANG = 58 P	
10 11	60 62 75	55 31₃ 53	61 61 75 80	59 50	67 88 59 69	62 59	70 49	76 60 53	65 61 50	591 521 583	56 58 45	AREA	MAR 64	APR	MAY 77	JUN	SAMPLE JUL 64		SEP 52				En
12	69	52 56	43	78 67 37	68	65 49 69	65 79 57	55 51	52 78	579 548	64 91	2 3	42 68 48	57 53 59 49 59 85	31 69 50	68 49 58 49 65 71	64 57 88 52 89 49	30 55 99	62 67 74 48	31 65 49	32 52 66	30M 564 376 577 550 561 571 576	
SUM	\$30	\$30	827	828	329	829	830	329	330	7401	829	5  7	42 48 48 92 48 75	49 58 85	31 69 50 57 68 89 53	55	39 49 72 58	87 30 55 99 84 60 96 74	48 67 61 84 79	00T 82 81 65 49 105 62 41 54	NOV 58 32 52 66 63 94 49 73	561 571 576	
AREA I	MAR 778 670	APR 1051 1057	MAY 958 525	JUN 1180 384	)PULATIO JUL 502 752	AUG o67	SEP 617 519	00T 540 644	NOV 412 488	5UM 5705 5235	AVE 745 673	3	63 53	61 54	59	63 74	64	58	79 51 543	54 56 545	73 51 54\$	583 530 4888	
8 4 5	362 415 521	539 428 919	349 559	565 565 733 879	357 434	596 588 515 584	341 443	296 284	439 346 441	3836 4088 5516	426 454	SUM	548	548	543	542	548 OPULATIO	548 ON SIZE	743	545	745	4000	
0 7 8 6	947 372 492	1036	614 335 575 579 710	959 910	602 951 661 402 745	584 627 692 525 680 809	535 538 506 330 503	507 683 445 492	687 426	6983 5271 4586	613 765 596 510	AREA I	MAR 445 82	AFR 494 39	MAY 672 63 726	JUN 667 144	JPULATTI JUL 578 146	AUG ∌58 61	SEP 534 161	00T 761 73	NOV 542 78	SUM 5051 897	
10 11 12	645 291 550	785 582 822 170 593	710 341 779 789	336 336 977	463 583	2.5	200 502	654 248 409	304 516 233 425 345	5211 2591 5550	590 238 617 577	3 4 5	974 276	558 644 393	726 363 458	688 427 648	982 392 329	648 802 306	781 343 540	733 375 911	589 513 553	6274 418 <b>5</b> 4669	
1.3	541 396	508 419	435	792 302	441	446 446	571 283	401 257	366	5192 3350	372	ં 7 ઉ	531 373 414 414	563 370 737	363 458 661 711 645	847 690 937	500 7 <b>74</b> 738	044 1095 999	587 334 951	643 447 699	984 537 1020	5802 5072 7340	
SUM SEGION CHICAGO	6750 5	9014	3047	7818	7537	7407	5993	6020 DE		CHANGE	73 <b>35</b> CASE	S SUM	245 37 <b>54</b>	306 46 <b>54</b>	396 4695	522 5570	383 4 <b>822</b>	374 5282	292 4523	341 49 <b>9</b> 3	316 5132	\$175 43415	
AREA 1	MAR 30	APR 32	MAY 62	JUN 72	SAMPLE JUL 56	SIZE AUG 54	SEP 56	OCT	F RATE NOV 53	* 48 PE SUM 468	AVE 52	REGIO SEATT	N 10							ne	F RATE	CHANG = 55 P	
2 3	93 46 92 95	32 30 52 69 94	62 42 54 43	46 72	JUL 56 53 60 68	57 55	56 79 46 43	53 30 60 48 52 49 52	69 52 70 46	561 509	6≩ 57	AREA	MAR 57	APR 50	MAY 52	JUN 59	SAMPLI JUL 50	E SIZE AUG 56	SEP 58	ост	NOV 57 50 49		
4 5 7	95 54 52 34	94 9 49	59 65 90	56 75 44	98 34 49	31 36 73	66 45 59	52 49 52	46 66 77	560 587 543 548 548 545	65 60 60	3	50 49	50 53 53	MAY 58 57 47	56 42	52 55	48 53	58 44 54	55 40 61			
8 0 10 11	130	49 47 72 35 105	54 43 59 65 90 65 70 73 56 63 69	62 56 75 44 62 44 53 84 62	93 93 34 49 34 30 99 54 50	60 38 60	66 45 58 70 48 47 64	61 61 48 45	66 77 65 52 61 58 50 58	548 545 529 580	61 59 64	SUM	156	156	157	157	157	157	156	156	156	1408	
11 12 18 14	46 30 49	47	56 63 69	34 62 61 51	54 50 30	69 57 65 31 86 73 60 88 60 68 53 57	9.4 75	123 49	58 50 58	594 496	56 55	AREA	MAR 246	APR 354	MAY 329	JUN 398	OPULATIO JUL 252	272	SEP 237	00T 200	NOV 204	SUM 2492	
:4	37 341	3 <b>3</b> 3 <b>4</b> 3	30 941	51 344	38 942	71 848	82 843	63 344	943	521 7584	58 843	2 3 4194	131 143	279 284	262 217	275 210	194 211	170 192 634	131 166 534	109 170 479	133 134 471	1734 1727 5953	
												SUM	. 570	717	308	383	657	534	334	4/4	4/1	24.23	

# EXHIBIT 2 (Continued)

MATION											E CASE
141.1014								D	EF RATE	= 51 8	ERCENT
					SAMPLI	E SIZE					
REGION	MAR	APR	MAY	JUN	JUL	AUG	SEP	OCT	NQV	SUM	AVE
1	230	231	232	232	232	231	232	232	231	2083	231
2	497	498	498	499	499	499	500	499	493	4487	499
2	462	4-01	468	462	461	452	462	462	463	4158	4.62
4	830	830	327	828	928	329	830	829	330	7461	329
5	341	343	341	344	342	343	343	344	343	7584	848
	196	198	196	190	195	197	196	197	196	1767	196
÷	519	518	518	518	513	518	519	513	518	4664	518
8	160	161	161	161	161	161	160	160	160	1445	161
ė	543	543	543	542	543	543	543	545	543	4893	543
10	15é	156	157	157	157	157	156	156	156	1408	156
NATION	4434	4439	4436	4439	4436	4440	4441	4442	4438	39945	4438
				P	OPULATI	ON SIZE					
REGION	MAR	APR	MAY	JUN	JUL	AUG	3EP	OCT	NOV	SUM	AVE
1	1532	2223	2202	3048	2347	2776	3214	2592	2619	22553	2506
ż	2343	4047	3517	4147	3005	2801	2259	1879	1631	25629	2846
3	24.81	3154	2499	2731	2329	1838	1451	1423	1482	19338	2149
3	6750	9014	3047	9818	7537	7407	5993	6020	5428	56014	7335
5	50⊲3	6163	5044	5425	3630	3506	2998	3046	2779	37654	4184
ق ا	341	1156	1041	1189	948	1065	770	659	623	8297	922
7	6501	7862	6330	7440	5401	5166	4218	4062	4013	50543	5614
8	541	347	397	782	591	651	417	421	341	5238	582
- 5	3754	4654	4695	5570	4822	5282	4523	4983	5132	43415	4824
10	570	917	908	883	657	5.34	534	479	471	5953	001
NATION	30325	29537	34990	40983	31267	31126	26377	25564	24524	284634	31026

9 MONTH ROLL SAMPLING ERRORS 4 MONTH ROLL SAMPLING ERRORS CHANGE CASE CHANGE CASE

CHANGE CASE		CHANGE							
DEF RATE = 51 PERCENT	MAR-		TE = 51 PERCENT	MAR-	APR-	MAY-	JUN-	JUL-	AUG-
REGION AND AREA	NOV	REGION	AND AREA	JUN	JUL	AUG	SEP	OCT	NOV
1 1 BOSTON	3.97	1 1	BOSTON	5.71	5.79	5.87	0.16	6.19	6.29
1 2 BOSTON	3.99	i î		0.53	0.27	6.15	5.88	5.70	5.49
1 B BOSTON	3.98	i ē		6.19	6.02	5.98	5.80	5.74	5,30
1 4 BOSTON	3.97	1 4		5.62	5.73	5.82	6.09	0.24	6.42
	3.98	2 1		5.17	5.91	5.36	5.30	5.50	5.52
2 1 NEW YORK 2 2 NEW YORK	3.98	2 2		4.26	5.38	5.65	5.59	5.45	5.40
2 3 NEW YORK	3.98	2 3		5.70	5.84	5.91	€.07	5.81	5.89
2 4 NEW YORK	3.98	2 4		5.32	5.64	5.67	5.63	5.65	5.30
2 5 NEW YORK	3.76	2 5		6.21	6.23	5.31	5.56	5.43	5.42
2 5 NEW YORK 2 7 NEW YORK	9.98 3.98	2 6		5.63	6.06	6.09	6.11	5.72	5.68
	3.98			6.03	6.04 5.46	5.63	5.93	5.95	5.05
2 9 NEW YORK 3 1 PHILADELPHIA	3.78		NEW YORK PHILADELPHIA	5.70 5.93	6.23	0.02	6.01	5.71	5.34
3 2 PHILADELPHIA	3.97	3 1		5.64	5.57	5.73	5.70	5.81	5.74
3 S PHILADELPHIA	2.72	3 3		6.77	5.54	6.46	5.91	5.32	4.67
4 PHILADELPHIA	3.98	3 4		5.67	5.55	5.46	5.65	5.36	5.93
5 PHILADELPHIA	3.98		PHILADELPHIA	6.02	5.34	5.70	5.71	5.48	5.24
D PHILADELPHIA	3.93	3 6	PHILADELPHIA	5.83	5.00	5.75	5.31	5.76	5.37
3 7 PHILADELPHIA	3.78	3 7		5.75	5.89	5.79	5.83	5.64	5.35
3 8 PHILADELPHIA	3.98		PHILADELPHIA	6.24	5.56	6.32	6.23	5,49	4.93
4 1 ATLANTA	3,99	4 1		5.47	5.76	5.99	6.16	6.31	6.21
4 2 ATLANTA	3.99	4 2		5.98	5.97	6.22	6.07	5.84	5.38
4 3 ATLANTA	3.98	4 3		6.22	6.30	0.05	5.90	5.39	5.49
4 4 ATLANTA	3.98	4 4		6.15	6.18	5.94	5.91	5.74	5.54
4 5 ATLANTA 4 o ATLANTA	3.99	4 5		5.98	5.95	6.21	6.12	5.94	5,30
4 5 ATLANTA 4 7 ATLANTA	3.99	4 6		6.15	5.84	5.76	5.68	5.70	5.75
4 8 ATLANTA	3.98	4 9		5.69	5.83	5.30	6.01	6.01	5.96
4 PATLANTA	3.98	4 9		6.10	6.06	6.10	6.04	5.76	5.75
4 :0 ATLANTA	3.98	4 10		6.41	6.02	5.68	5.33	5.80	5.87
4 11 ATLANTA	3.99	4 11	ATLANTA	5.73	5.33	5.76	5.90	0.10	6.06
4 12 ATLANTA	3.99	4 12		5.77	5.72	5.36	5.92	5.95	6.12
4 13 ATLANTA	3.97	4 13		6.22	6.22	6.03	6.12	5.87	5.70
5 1 CHICAGO	3.96	5 1		6.18	5.82	5.49	5.51	5.21	5.12
5 2 CHICAGO 5 8 CHICAGO	3.98	5 2		5.31	7.17	5.67	5.94 5.73	5.33	5,14
5 4 CHICAGO	3.98	5 4		5.68	6.01	6.01	5.00	5.86	5.79
5 5 CHICAGO	3.98		CHICAGO	5.41	5.54	6.21	6.11	5.89	0.41
5 6 CHICAGO	3.98	5 6		5.63	5.29	5.06	5.39	5.35	5.40
5 7 CHICAGO	3.98	5 7		5.97	6.06	5.73	5.00	5.00	5.27
5 8 CHICAGO	3.98	5 9	CHICAGO	6.39	5.78	5.00	5.52	5.24	5.36
5 9 CHICAGO	3.99	5 9		5.14	6.32	6.34	7,27	6.34	5,97
5 10 CHICAGO	3,98		CHICAGO	6.21	5.66	5.36	5.56	5.35	5.70
5 11 CHICAGO 5 12 CHICAGO	3.98	5 11		5.50	5.40	5.82	5.75	5.90	5.30
	3.98		CHICAGO	6.02	5.74	6.27 5.99	6.27 5.82	5.29 5.30	5.25
5 13 CHICAGO 5 14 CHICAGO	3,97	5 13 5 14	CHICAGO CHICAGO	5.85 7.41	6.42	5.79	5.23	4.88	4.99
: PANSAS CITY	3,98	6 1		5.94	5.36	5,94	5.31	5.79	5.37
2 MANSAS CITY	3.97	š 2		5.72	5.53	5.71	6.01	6.09	6.08
B YANSAS CITY	3.98	6 3		5.91	0.01	5.91	5.82	5.89	5.89
4 HANSAS CITY	3.97	6 4	KANSAS CITY	5.32	6.47	6.16	5.12	5.69	5.48
1 DALLAS	3.98	7 1		5.82	5.67	5.57	5.73	5.85	5.32
7 2 DALLAS	3.98	7 2		5.29	6.21	6.18	6.01	5.62	5.37
5 DALLAS	3,98	7 3		6.07	5.77	5.66	5.77	5.58 5.91	5.74
	3.99	7 4	DALLAS	5.73	6.09 5.57	6.00 5.65	6.07 5.59	5.48	5.32
7 5 DALLAS 7 6 DALLAS	3.78	7 5		6.19	6.06	6.11	6.15	5.72	5.46
7 7 DALLAS	3.98	7 7		5.54	5.94	6.09	5.98	6.17	6.06
7 8 DALLAS	3.98	7 8		5.47	6.04	6.10	6.35	5.23	6.00
3 1 DENVER	3.98	8 1		5.95	5.93	5.84	5.86	5.73	5.67
8 2 DENVER	3.97	8 2	DENVER	5,95	5.93.	5.33	5.35	5.70	5.03
8 3 DENVER	3.97	8 3		5.96	5.94	5.32	5.83	5.68	5.61
9 1 SAN FRANCISCO	3.98	9 1		5.88	5.36	6.10	5.30	6.02	6.10
9 2 SAN FRANCISCO 9 8 SAN FRANCISCO	3.97	9 3		0.18	5.96	6.08	5.50 5.82	5.62	5.98 6.08
9 8 SAN FRANCISCO 9 4 SAN FRANCISCO	3.98	9 3		6.17	5.89 6.02	5.91	5.94	5.92	5.76
9 5 SAN FRANCISCO	9.98	3 9		6.09 5.96	6.51	6.76	6.60	5.99	5,72
9 - SAN FRANCISCO	3.99	9 6		6.12	2.03	6.06	0.14	6.23	5.70
9 7 SAN FRANCISCO	3.98	9 7		5.69	5.69	5.59	5.96	0.11	0.42
9 8 SAN FRANCISCO	રૂ.જજ	9 8	SAN FRANCISCO	6.25	6.28	0.11	5.32	5.39	5.08
9 9 SAN FRANCISCO	3.98	9 9		5.33	5.03	5.55	5.85	5.03	0.22
1) : EATTLE	5.98		SEATTLE	0.00	0.06	5.94	5.87	5.72	5.56 5.33
10 I SEATTLE	3.78		SEATTLE SEATTLE	5.75 6.31	5.77	5.78	5.94	5.40	5.36
10 3 SEATTLE	3.97	10 3	DEATTLE	0.01	9.09	3.00	2.00	3.40	0.00